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# Introduction to Spectral Graph Theory

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### Graphs

#### Definition

A graph is a pair G = (V, E), where V is a set whose elements are called vertices and E is a set of paired vertices, whose elements are called edges.



## Graphs

We will (mostly) consider cases where G:

- is finite
- has no  $v \in V$  s.t.  $\deg(v) = 0$
- could have self-loops and parallel edges
- is not necessarily connected
- unweighted



# Adjacency matrix

#### Definition (Adjacency matrix)

Let  $\mathcal{G}$  be a graph with vertices  $v_1, v_2, \ldots, v_n$ . Then the *adjacency* matrix of  $\mathcal{G}$  is the matrix  $A \in Mat(n \times n; \{0, 1\})$ , whose (i, j) entry, denoted by  $[A]_{i,j}$ , is defined by

$$[A]_{i,j} = \begin{cases} 1 & \text{if } v_i \text{ and } v_j \text{ are adjacent} \\ 0 & \text{otherwise.} \end{cases}$$

# A network analysis of Spotify [SRM'21]

- A network of all the artists on Spotify connected by who they worked with
- 1,250,065 artists (vertices on undirected graph)
- 3,766,631 collaborations (edges on undirected graph)
- Snowball sampling starting with Kanye West
- Get metadata on these artists (eg popularity, etc)
- Represent using adjacency matrix:

$$A = \begin{array}{cc} \text{Kanye} & \text{Drake} & \text{Taylor} \\ A = \begin{array}{cc} \text{Drake} \\ \text{Taylor} \end{array} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{array} \end{pmatrix}$$

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**Relative popularity** 



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## **Eigenvector** centrality

• Calculate the eigenvector centrality:  $Av = \lambda v$ 



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## Filter popularity + eigenvector centrality

• Take the most popular contemporary artists



Figure 1: Dominance shifts from classical music to rappers.

## When does it all change?

- Delete nodes with a popularity of 10 or less
- Nothing changes in critical region, but location of the transition is shifted
- Even unpopular artists can change the structure of graph!



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# Why? It's all in the eigenvalues

• The vectors representing classical dominance and rap dominance exist the entire time, but they change ranking:



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## **Graph Laplacian**

#### Definition (Laplacian matrix)

Define the degree matrix  $D \in Mat(n \times n; \mathbb{R})$  as

$$D_{i,j} = egin{cases} \deg(v_i), & ext{if } i=j \ 0, & ext{otherwise}. \end{cases}$$

The Laplacian matrix is then defined as L = D - A.

• Analogous to analytic definition of the Laplacian!

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## A function on graphs

- Suppose a function  $f: V \to \mathbb{R}$  on G:
  - could be voltage, temperature, 0/1 indicator for a subset  $S\subseteq V$ , etc...

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# A function on graphs

- Suppose a function  $f: V \to \mathbb{R}$  on G:
  - could be voltage, temperature, 0/1 indicator for a subset  $S \subseteq V$ , etc...
- ...then would have

$$f: V \to \mathbb{R} \equiv \begin{bmatrix} f(v_1) \\ f(v_2) \\ \vdots \\ f(v_n) \end{bmatrix}$$

• f acting on V behaves like  $\mathbb{R}^n$  and forms a vector space.

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#### Local variance

#### Definition (Local variance)

The *local variance* of *f* is defined as:

$$\mathcal{E}(f) := \mathbb{E}_{u \sim v} \left[ \left( f(u) - f(v) \right)^2 \right],$$

where  $u \sim v$  is a probability distribution over the edges.

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 $\implies \mathcal{E}(f)$  is "small" iff f is "smooth" over the edges.

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Can immediately observe that:

- $\mathcal{E}(f) \geq 0$
- $\mathcal{E}(c \cdot f) = c^2 \cdot \mathcal{E}(f)$
- $\mathcal{E}(f+c) = \mathcal{E}(f)$ .

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#### Local variance: example

Let  $S \subseteq V$  and  $f = \mathbb{1}\{v \in S\}$ .

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Local variance: example

Let  $S \subseteq V$  and  $f = \mathbb{1}\{v \in S\}$ .

The local variance is then

$$\begin{split} \mathcal{E}(f) &= \frac{1}{2} \cdot \mathbb{E}_{u \sim v} \left[ (\mathbbm{1}\{u \in S\} - \mathbbm{1}\{v \in S\})^2 \right] \\ &= \frac{1}{2} \cdot \mathbb{E}_{u \sim v} \left[ \mathbbm{1}\{(u, v) \text{ "crosses" } S\} \right] \\ &= \frac{1}{2} \cdot \{\text{fraction of edges on } \partial S\} \\ &= \mathbb{P}_{u \sim v}\{u \to v \text{ is "stepping" out of } S\}. \end{split}$$

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## **Random** Vertices

- Procedure for choosing a random vertex:
  - Choose  $\mathbf{u} \sim \mathbf{v}$  a random edge.
  - Output **u**.



#### **Random Vertices**

- Procedure for choosing a random vertex:
  - Choose  $\mathbf{u}\sim\mathbf{v}$  a random edge.
  - Output **u**.
- This stationary distribution on the vertices, π, prioritises vertices based on the number of adjacent edges (evenly spread probability only in the case of regular graph).



- The probability of picking u,  $\pi(u)$ , is proportional to  $\deg(u)$ . (In fact it is  $\pi(u) = \deg(u)/2|E|$ .)
- The process of picking u from π and then picking v as a uniformly random neighbour of u is the same as drawing an edge uniformly at random u ~ v.
- Let t ∈ N. Pick u ~ π. Now do a random walk starting at u taking t steps. Then the distribution of v, the endpoint of the walk, is π. (π is invariant.)

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## The Spectral Theorem

We say that  $\nu$  is an eigenvector of  $M \in Mat(n \times n; \mathbb{R})$  with eigenvalue  $\lambda$  if  $M\nu = \lambda \nu$ .

Then  $\lambda$  is an eigenvalue iff  $\lambda \mathbb{I} - M$  is singular.

### Theorem (Spectral Theorem)

If *M* is an n-by-n, real, symmetric matrix, then there exist real numbers  $\lambda_1, \ldots, \lambda_n$  and n mutually orthogonal unit vectors  $\nu_1, \ldots, \nu_n$  and such that  $\nu_i$  is an eigenvector of *M* of eigenvalue  $\lambda_i$ , for each *i*.

## **Proof Sketch: Induction**

If n = 1, then  $M = \lambda$  and can pick any  $v \neq 0$  as a basis for  $\mathbb{R}$ .

**Hypothesis.** Every k-by-k matrix for k = 1, ..., n-1 satisfies the spectral theorem.

# Step.

- Obtain orthonormal basis  $B = v_1, \ldots, v_n$  for  $\mathbb{R}^n$  by choosing  $\lambda_1 \in \mathbb{R}$
- Use  $P = \begin{bmatrix} v_1 & \dots & v_n \end{bmatrix}$  to obtain a block form for  $A = P^\top M P$
- Then show that ∃ orthogonal R s.t. R<sup>T</sup>MR is diagonal via induction hyp. ⇒ ∃ orthonormal basis for ℝ<sup>n</sup> consisting of eigenvalues of M.

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# Cover time of graph

Given, for graph G:

- Laplacian matrix L = D A
- Eigenvalues  $0 = \lambda_1 \leq \lambda_2 \leq \ldots \leq \lambda_n$
- Eigenvectors  $\nu_1$ ,  $\nu_2$ , ...,  $\nu_n$

**Problem.** Want to find how long it takes to cover G.

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### Cover time of graph

## Theorem (DLP'11)

If 
$$g_1, \ldots, g_n \sim_{\mathrm{i.i.d.}} \mathcal{N}(0, 1)$$
, then

$$n \cdot \left\|\sum_{i=2}^{n} \frac{g_i}{\sqrt{\lambda_i}} \cdot \nu_i\right\|_{\infty}^2 \asymp \text{ cover time of } G,$$

up to o(1) error.



Figure 2: Gaussian free field induced by graph

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## Unique games problems

**Problem:** Suppose you are given p prime and a family of 2-variate linear equations over the variables  $x_1, \ldots, x_n$ :

 $x_{13} - x_7 \equiv 4 \pmod{p}$   $x_4 - x_7 \equiv 9 \pmod{p}$   $x_7 - x_{12} \equiv 1 \pmod{p}$  $x_{11} - x_4 \equiv 0 \pmod{p}$ 

If 99% of these equations are satisfiable, then can we find a solution that works for 1% of these equations?

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## Unique games problems

**Conjecture** (Khot'02). This problem is computationally intractable.

The problem *can* be reduced to finding small clusters corresponding to specific  $\lambda$ .

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## Unique games problems

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Theorem (LOGT'12)

For  $S \subseteq V$ , let  $\phi_G(S) = |E(S, S^c)|/d|S|$ , and let the k-way expansion constant be

$$\rho_G(k) = \min_{S_1,\ldots,S_k} \max\{\phi_G(S_i) : i = 1,\ldots,k\}.$$

Then, for every graph G and every  $k \in \mathbb{N}$ ,

$$\lambda_k/2 \le \rho_G(k) \le \mathcal{O}(k^2)\sqrt{\lambda_k}$$

 $\implies$  Can always find small clusters!

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## Nearly linear-time Laplacian solver

#### **Problem**: Solve the system Lx = b.

- Will be culmination of seminar!
- We can quickly compute the spectral object *x* [ST'04, KMP'10, KOSZ'13]
- This in turn is useful for computing max flows and min cuts on a graph [CKMST'11, LSR'13, Madry'13, etc]

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#### Sign up for talks!!!

- 1. Courant-Fischer, graph Laplacian
- 2. Random walk
- 3. Electronic network
- 4. Sampling spanning tree
- 5. Graph sparsifier
- 6. Cheeger inequality
- 7. Laplacian solver
- 8. (Nearly) Linear-time Laplacian solver

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